Discovering Patterns by Searching for Simplicity

Alexander P.M. van den Bosch
Department of Philosophy and
Center for Behavioural, Cognitive and Neuro Sciences (BCN)
Groningen University
PA A-Weg 30, 9718 CW
Groningen - The Netherlands
E-mail: vdbosch@bcn.rug.nl

Abstract
I discuss the use of Kolmogorov complexity and Bayes' theorem in Solomonoff's inductive method to explicate a general concept of simplicity. This makes it possible to understand how the search for simple, i.e., short, computational descriptions of (empirical) data yields to the discovery of patterns, and hence more probable predictions. I show how the simplicity bias of Langley's BACON2 and Thagard's PI is subsumed by Rissanen's Minimum Description Length principle, which is a computable approximation of Solomonoff's uncomputable inductive method.

Introduction
This paper is about the role of simplicity in discovery, explanation, and predictions. I pursue and answer two questions: How can simplicity most generally be defined? And why should we prefer a simpler theory above a more complex one? I discuss simplicity definitions that stem from research in cognitive science and machine learning. In those approaches simplicity plays an important role in: the process of scientific discovery, as implemented in Langley and Simon's computer model BACON; inference to the best explanation, as implemented in Thagard's computer model PI; and in the probability of predictions, as explicated by Solomonoff.

Langley and Simon claim that the BACON programs search for simple consistent laws without making explicit what is meant by 'simple' laws and why we should pursue simplicity (Langley et al. 1987). Thagard proposed an explicit definition of simplicity and employs it in his model PI, without providing a satisfying reason for it (Thagard 1988). However Solomonoff proposed an explication of induction which makes use of a concept that can be used to understand simplicity and has a satisfying justification for its preference.

According to Solomonoff we should trust the theory which implications can be generated by the shortest computer-program that can generate a description of our known observational data. It is argued that a shorter computer-program provides more probable predictions because it uses more patterns from that data. It is proved that this simplicity measure is reasonably independent of the computer-language that is used. However it has one drawback, it is uncomputable. Yet it is claimed that computable approaches to induction in machine learning are approximations of Solomonoff's method (Li & Vitányi 1994).

In this paper I demonstrate how Solomonoff's approach can elegantly be used to make a universal prior probability distribution for Bayes' theorem. First it is shown that Rissanen's Minimum Description Length principle (MDL) can be derived from Solomonoff's approach. And from thereon I show that simplicity in Langley et al.'s BACON2, and simplicity in Thagard's PI are nicely subsumed by MDL.

An important general conclusion is that for any method that searches for regularities in data, it is justified, given found alternatives, to provisionally prefer the simplest explanation, i.e., the shortest computational description consistent with our observations.

Prior probabilities and programs
In 1964 an article by Solomonoff was published that contained a proposal for a general theory of induction. The objective was the extrapolation of a long sequence of symbols by finding the probability that a sequence is followed by one of a number of given symbols. It was Solomonoff's conviction that all forms of induction could be expressed in this form.

He argued that any method of extrapolation can only work if the sequence is very long and that all the information for an extrapolation is in the sequence. Solomonoff proposed a general solution that involved Bayes' theorem. This theorem requires that a prior probability of a hypothesis is known to determine the posterior probability with use of the known data. Solomonoff's solution is to provide for a universal distribution of prior probabilities, making use of a formal definition of computation.

It is widely believed that the notion of computation is fundamentally defined as the operation of a Turing-machine. This machine, conceived of by the mathematician Alan Turing, consists of a long tape and a finite automaton which controls a 'head' that can read, delete and print symbols on the tape. To
compute the value of a function \( y = f(x) \), write a program for \( f(x) \) on the tape, together with a symbolic representation of \( x \) and start the Turing-machine. The program is completed when the Turing-machine halts and the value of \( y \) is left on the tape as output. Turing proved that there is a universal Turing-machine that can compute every function that can be computed by any Turing-machine. The famous Church-Turing thesis claims that every function that can be computed, can be computed by a Turing-machine.

What Solomonoff did was to correlate all possible sequences of symbols with programs for a universal Turing-machine that has a program as input and the sequence as output. He assigned a sequence that can be computed with short and/or numerous programs a high prior probability. Sequences that need long programs and only has few, receive a low prior probability.

For Solomonoff the validity of giving a shorter program a higher prior probability is suggested by a conceptual interpretation of Ockham's razor. But it is justified because a shorter program utilises more patterns in the sequence to make the program smaller. So, if we trust the data as being representative of things to come, then the shorter program is the more probable.

If we, e.g., have a sequence that has \( x \) as a prefix and \( x = 12341234123412341234 \), then we could write a program that describes \( x \) as \( dadaa123 \), where \( d \) is a definition of 1234 as \( a \). If we want to predict the following letter we can entertain the hypothesis \( p_1 = dadaa123 \), or still shorter \( p_1 = d5\alpha \). Another option is \( p_2 = d4a1231 \). The first hypothesis predicts a 4 and the second a 1. Both hypotheses are compatible with the known data \( x \). Now Solomonoff argues that the prediction of \( p_1 \) is more probable because it requires a shorter program to generate a continuation of \( x \) than \( p_2 \) (Solomonoff 1964, p. 10).

That a sequence with many programs gets a high prior probability is suggested by the idea that if an occurrence has many possible causes, then it is more likely. The principle of indifference is integrated by giving programs of the same length the same prior probability.

Unfortunately this approach has as an important problem. It is not determinable if a given program is the shortest program that computes a sequence. If that was determinable then there would exist a Turing-machine that could determine for every possible program whether it would generate a given sequence. However, most of the possible Turing-machine programs will never halt. Due to this halting problem we cannot know for every program if the program computes a given sequence. But before I go into that problem I want to make Solomonoff's theory more specific by first discussing Kolmogorov complexity and its application in probability theory.

## Kolmogorov complexity

The Kolmogorov complexity of a sequence or string is actually a measure of randomness or, when inverted, the regularity of the patterns in that string. We can use a Turing-machine to measure that regularity with the length of the shortest program for that Turing-machine that has the sequence as output. We can call such a program a description of the sequence. This description is relative to the Turing-machine that has the description as input. So when we have a sequence \( x \) and a description program \( p \) and a Turing-machine \( T \) we can define the desriptional complexity of \( x \), relative to \( T \) as follows (cf. (Li & Vitányi 1993, p. 352)):

\[
C_T(x) = \min\{ l(p) : p \in \{0,1\}^*, T(p) = x \}
\]

or \( C_T(x) = \infty \) if no such \( p \) exists.

We consider \( T \) to be a Turing-machine that takes as input-program a binary string of zeros and ones, so the program is an element of the set \( \{0,1\}^* \), which is the set of all finite binary strings. We use binary strings because everything that can be decoded, like e.g., scientific theories, can be decoded with a string of zeros and ones. The length of the program, \( l(p) \), is the number of zeros and ones. So the definition takes as the complexity of a string \( x \) the program \( p \) that consists of the least number of bits and that will generate \( x \) when given to \( T \). If no such program exists then the complexity is considered to be infinite.

When \( x \) is a finite string then there is always a program that will describe it. Just take a program that will merely print the number literally. This program will be larger than the string. However, if \( x \) is infinite and no finite program exists, then \( x \) is uncomputable by definition.

This complexity measure is relative but surprisingly not (very) dependent on the Turing-machine that is used to describe a string, as long as it is a universal Turing-machine. Because there exists a universal Turing-machine that computes the same or a lower complexity than the complexity computed by every other Turing-machine plus some constant dependent on that Turing-machine. So e.g., when I have a string and two programs in different computer languages that compute that string, the difference in length between those programs cannot be more than a constant, independent of the string. This is called the invariance theorem (cf. (Li & Vitányi 1993, p. 353)).

In the literature Kolmogorov complexity \( K(x) \) is defined as a variant of desriptional complexity \( C(x) \), which makes use of a slightly different kind of Turing-machines. In the definition of desriptional complexity a Turing-machine was used with one infinite tape that can move in two directions and that starts with an input program on it and halts with a string on the tape as output. For the definition of Kolmogorov complexity
Bayesian inference

We will start with a hypothesis space that consists of a countable set of hypotheses which are mutually exclusive, i.e., only one can be right, and exhaustive, i.e., at least one is right. Each hypotheses must have an associated prior probability \( P(H_n) \) such that the sum of the probabilities of all hypotheses is one. If we want the probability of a hypothesis \( H_n \) given some known data \( D \) then we can compute that probability with Bayes’ formula:

\[
P(H_n|D) = \frac{P(D|H_n)P(H_n)}{P(D)}
\]

where \( P(D) = \sum_n P(D|H_n)P(H_n) \). This formula determines the \textit{a posteriori} probability \( P(H_n|D) \) of a hypothesis given the data, i.e., the probability of \( H_n \) modified from the prior probability \( P(H_n) \) after seeing the data \( D \). The conditional probability \( P(D|H_n) \) of seeing \( D \) when \( H_n \) is true is usually forced by \( H_n \), i.e., \( P(D|H_n) = 1 \) if \( H_n \) can generate \( D \), and \( P(D|H_n) = 0 \) if \( H_n \) is inconsistent with \( D \). So when we only consider hypotheses that are consistent with the data the prior probability becomes crucial. Because for all \( H_n \) where \( P(D|H_n) = 1 \) the posterior probability of \( H_n \) will become:

\[
P(H_n|D) = \frac{P(H_n)}{P(D)}
\]

Now let us see what happens when we apply Bayes’ formula to an example of Solomonoff’s inductive inference. In this example we only consider a discrete sample space, i.e., the set of all finite binary sequences \( \{0,1\}^* \). What we want to do is, given a finite prefix of a sequence, assign probabilities to possible continuation of that sequence. What we do is, given the known data, make a probability distribution of all hypotheses that are consistent with the data. So if we have a sequence \( x \) of bits, we want to know what is the probability that \( x \) is continued with \( y \). So in Bayes’ formula:

\[
P(xy|x) = \frac{P(xy|x)P(xy)}{P(x)}
\]

We can take \( P(x|xy) = 1 \) no matter what we take for \( y \), so we can say that:

\[
P(xy|x) = \frac{P(xy)}{P(x)}
\]

Hence if we want to determine the probability that sequence \( x \) is continued by \( y \) we only need the prior probability distribution for \( P(xy) \). Solomonoff’s approach is ingenious because he first identifies \( x \) with the computer programs that generate \( xy \). In this way \( y \) can be determined in two ways: \( y \) is the next element that is predicted, i.e., generated, by the smallest Turing-machine program that can generate \( x \); or the element is predicted that is generated by most of the programs that can generate \( x \).

So we can define the prior probability of a hypothesis in two different ways. We can give the shortest program the highest prior probability and define the probability of \( xy \) as:

\[
P_K(xy) := 2^{-K(xy)}
\]

i.e., the length of the shortest program that computes \( xy \) as the negative power of two (Li & Vitányi 1990, p. 216). Or we can define \( P_L(x|y) \) as the sum of \( 2^{-L(p)} \) for every program \( p \) (so not only the shortest) that generates \( xy \) on a reference universal prefix machine (Li & Vitányi 1993, p. 356). The latter is known as the Solomonoff-Levin distribution. Both have the quality that the sum of prior probabilities is equal to or less than one, i.e., \( \sum_x P_K(x) \leq 1 \) and \( \sum_x P_L(x) < 1 \). However, it can be shown that if there are many ‘long’ programs that generate \( x \) and predict the same \( y \), then a smaller program must exist that does the same. And it is proved that both prior probability measures coincide up to an independent fixed multiplicative constant (Li & Vitányi 1993, p. 357).

So we can take the Kolmogorov complexity of a sequence as the widest possible notion of shortness of description of that sequence. And if we interpret shortness of description, defined by Kolmogorov complexity, as a measure for parsimony, then the Solomonoff-Levin distribution presents a formal representation of the conceptual variant of Ockham’s razor. Because the predictions of a simple, i.e., short, description of a phenomenon are more probable than the predictions of a more complex, i.e., longer, description.

Minimising the description length

While both the Kolmogorov and Solomonoff-Levin measure are not computable, there are computable approximations of them. It is demonstrated that several independently developed inductive methods are actually computable approximations of Solomonoff’s method (Li & Vitányi 1993). I will first demonstrate this for Rissanen’s MDL.

Rissanen made an effort to develop an inductive method that could be used in practice. Inspired by the
ideas of Solomonoff he eventually proposed the minimum description length principle. This principle states that the best theory given some data is the one which minimizes the sum of the length of the binary encoded theory plus the length of the data, encoded with the help of the theory. The space of possible theories does not have to consist of all possible Turing-machine programs, but can just as well be restricted to polynomials, finite automata, Boolean formulas, or any other practical class of computable functions.

To derive Rissanen’s principle I first need to introduce a definition of the complexity of a string given some extra information, which is known as conditional Kolmogorov complexity:

**Definition 2** The conditional Kolmogorov complexity $K_T$ of $x$, relative to some universal prefix Turing-machine $T$ and additional information $y$ is defined by:

$$K_T(x|y) = \min \{ \ell(p) : p \in \{0,1\}^*, T(p,y) = x \}$$

or $K_T(x|y) = \infty$ if such $p$ does not exist.

This definition subsumes the definition of (unconditional) Kolmogorov complexity when we take $y$ to be empty. Now, Rissanen’s principle can elegantly be derived from Solomonoff’s method. We start with Bayes’ theorem:

$$P(H|D) = \frac{P(D|H)P(H)}{P(D)}$$

The hypothesis $H$ can be any computable description of some given data $D$. Our goal is to find an $H$ that will maximise $P(H|D)$. Now first we take the negative logarithm of all probabilities in Bayes equation. The negative logarithm is taken because probabilities are given the hypothesis, plus the description length of the hypothesis ($\ell(H)$), approximated by the probability for the shortest program for $H$, i.e., the Kolmogorov complexity $K(H)$. The same goes for $P(D|H)$ and hence we should minimise:

$$-\log P(D|H) - \log P(H)$$

This will result to the Minimum Description Length principle if we consider that the probability of $H$ is approximated by the probability for the shortest program for $H$, i.e., $P(H) = 2^{-K(H)}$. Therefore the negative logarithm of the probability of $H$ is exactly matched by the length of the shortest program for $H$, i.e., the Kolmogorov complexity $K(H)$. The same goes for $P(D|H)$ and hence we should minimise:

$$K(D|H) + K(H)$$

i.e., the description or program length of the data, given the hypothesis, plus the description length of the hypothesis ($\ell(H)$). To make this principle practical all that remains is formulating a space of computable hypotheses that together have a prior probability smaller or equal to one, and searching this space effectively. It has been shown in several applications that this approach is an effective way of learning (Li & Vitányi 1993, p. 371).

### BACON and PI

Let’s look at the simplicity bias of BACON 2 (BACON 2) is not representative for the other BACON programs. I discuss the simplicity bias of the other BACON’s in (Van den Bosch 1994). BACON 2 will always construct the simplest consistent law in its range of search. The method it uses is called the differencing method. With this method BACON 2 is able to find polynomial and exponential (polynomial) laws that summarise given numeral data (Langley et al. 1987). One could define BACON 2’s simplicity bias as follows:

**Definition 3** The simplicity of a polynomial in BACON 2 decreases with the increase of the polynomial’s highest power. And, when possible, a variable power will result to a simpler polynomial than a polynomial with a high constant degree.

Langley et al. give no epistemical reason for preferring simplicity. However, after discussing simplicity in Thagard’s PI I will argue that BACON 2 its simplicity bias as defined above, is justified.

Thagard’s account of the simplicity of a hypothesis does not depend on the simplicity of the hypothesis itself, but on the number of auxiliary hypotheses that the hypothesis needs to explain a given number of facts (Thagard 1988). In PI, Thagard’s cognitive model of scientific problem solving, discovery and evaluation are closely related. Simplicity plays an important role in both.

**Definition 4** The simplicity of hypothesis $H$, with a number of $c$ co-hypotheses and $f$ facts explained by $H$, is calculated in PI as $\text{simplicity}(H) = (f - c)/f$ or zero if $f \leq c$.

To assess the best explanation PI considers both consilience (i.e., explanatory success, or in PI; number of facts explained) and simplicity. This is no difficult decision if one of the dimensions is superior while the values for the other dimension are more or less equal. If both explain the same number of facts but one is simpler than the other, or if they are both equally simple, but one explains more facts than the other, then there is no difficult choice. But when e.g., the first theory explains most facts while the second is the simplest, that conflict seems to make the choice more difficult. In that case PI computes a value for both hypotheses according to the following definition:

**Definition 5** The explanatory value of hypothesis $H$ for IBE is calculated in PI as $\text{value}(H) = \text{simplicity}(H) \times \text{consilience}(H)$.

In this way PI can pick out explanations that do not explain as much as their competitors but have a higher
simplicity or explain more important facts. It also renders ad hoc hypotheses useless because if we add an extra hypothesis for every explanation then the simplicity of that theory will decrease at the same rate as the consilience.

One feature of IBE in PI is that its valuation formula implies a much simpler definition which easily follows from the definitions of the simplicity and the value of a hypothesis:

**Definition 6** For IBE the explanatory value of a hypothesis \( H \), for the number of \( c \) co-hypotheses and \( f \) facts explained, can be calculated in PI as value\((H) = f - c \), or zero if \( f \leq c \).

Thagard does not satisfactorily argue why we should prefer this kind of simple hypotheses. He only demonstrates that several famous scientists used it as a defending argument. But he did not show that simplicity promotes the goals of inference to the best explanation, like truth, explanation and prediction.

**Approximation**

I will now compare Rissanen's minimum description length principle (MDL) with BACON.2, and with inference to the best explanation (IBE) as implemented by Thagard in PI.

For BACON.2 Rissanen's principle suggests an improvement because in the case of noisy data, BACON.2 would probably come up with a polynomial as long as that data, while it could construct a much simpler one when it employs and decodes deviations from the polynomial as well.

An important difference between Rissanen's principle and BACON is that the former requires to search the whole problem space, while the latter searches it heuristically. But BACON's search is guided by the same patterns that eventually will be described by a law. However, a heuristic search, like BACON's, can be aided by Rissanen's principle. Actually BACON does search for a minimal description, but it does not try to minimise it, i.e., if BACON finds a description, it halts, and will not search for a shorter one.

BACON.2 determines the shortest polynomial that can describe a given sequence. A Turing-machine can be constructed that needs a longer description for a more complex polynomial. It can be demonstrated that a polynomial with an exponential term needs a shorter description than a non-exponential polynomial that describes the same sequence. BACON.2's method always finds the simplest polynomial that exactly fits the data. So I will make the following claim:

**Claim 1** The polynomial constructed by BACON.2 with the differencing method, based on a given sequence \( x \), is the polynomial with the shortest description that exactly describes \( x \), if \( x \) can be described at all with a polynomial.

The validity of this claim can be derived from the differencing method. Every preference of BACON.2 between two polynomials that are compatible with the data is in agreement with the minimum description length principle. However, MDL can seriously improve BACON.2 by including a valuation of a description of the sequence, given a possible polynomial. A shorter description of the sequence may result when deviations from a possible polynomial are encoded as well.

In Thagard's explication of inference to the best explanation, in PI the simplicity of a hypothesis is determined by the number of additional assumptions or co-hypotheses that the hypothesis needs for its explanations. Rissanen's MDL accounts for the importance of auxiliary hypotheses as well. MDL requires that we minimise both the description of an explaining hypotheses and the description of the data with the aid of the hypothesis. If an hypothesis can explain something right away the description of the data is minimal, while if the hypothesis requires additional assumptions, the description of the data will be longer. So Thagard's simplicity satisfies at least one of the requirements of MDL. Hence I want to make the following claim and argue for its plausibility.

**Claim 2** In case of equal consilience, the explanation that will be selected by IBE in PI will provide a shorter description of the facts, given the explanation, or at least no longer description with respect to the available alternatives.

This claim follows easily from the definition stating that PI's IBE values hypotheses by subtracting the number of co-hypotheses \( c \) from the number of \( f \) explained facts, i.e., \( f - c \). Two hypotheses that are of equal consilience explain the same number of facts, in which case the hypothesis with the least number of co-hypotheses is preferred. Hence, assuming that every such extra assumption is of reasonably equal length, the simpler hypothesis will provide a shorter description of the facts given the hypothesis. However, if both have the same number of co-hypotheses, then PI can not make a choice, because both will provide a description of reasonably similar length.

Note that the length of description of the hypothesis is not relevant in this description of the facts. An approximation of the first clause, \( K(D|H) \) is minimised and not the second clause, \( K(H) \). Recall that the conditional Kolmogorov complexity \( K(D|H) \) is defined as the shortest program that will generate \( D \), with the aid of \( H \). Such a program will be of length zero if \( H \) can generate \( D \) on its own. Hence the shortest program that generates \( D \) given \( H \) is an effective measure of the length of the co-hypotheses that are needed by \( H \) to explain \( D \).

**The simplest hypothesis**

One question may now come to mind: will the Solomonoff approach yield a unique preference when several simple hypotheses are compatible with the data? It seems possible that more than one theory
or program, consistent with given data, can be of the same length. So in that case we cannot make a decision based on a simplicity consideration, because all alternatives are of equal simplicity.

To answer that critique we first have to distinguish between the next symbol $y$ that is predicted given a sequence $x$ and the different programs $p$ that can generate a prediction. Our goal can be a proper prediction $y$, given $x$, or a proper explanation of $x$. In the case of the need of a proper prediction, if two programs are of the same length it may turn out that both predict something else. However, Solomonoff's method supplies two ways to solve this dilemma.

The first is the universal Solomonoff-Levin distribution with which probabilities can be assigned to different continuations of a sequence. A given prediction $y$ not only receives a higher probability if it is predicted by a short program, but also if numerous programs make the same prediction. So if there is more than one shortest program, the prediction of the program that predicts the same as numerous other longer programs is preferred.

The second way out of the dilemma is in the situation when the given amount of data $x$ is very long. It can be proved that in the limit all reasonable short programs will converge to the same prediction, so you can pick any of them. This feature of the Solomonoff approach is nice for practical and computable approximations. Because you can make reasonably good predictions with a given short program that may not be the shortest one.

However, if you value the best explanation of a given amount of observations, then you won't be satisfied by a grab-bag of possible hypotheses that may not even make the same predictions. Scientists that want to understand the world usually look for one best explanation. In this situation a case could be made for the simplest hypothesis as the best explanation. But with such an aim the Solomonoff approach seems troublesome. Because you can never know whether a given short program that computes $x$ is also the shortest program possible. Because the only effective way to do so is to test all possible Turing-machines one by one to see if they generate $x$. But any of those possible Turing-machines may never halt and there is no way to find out if it ever will. You may put a limit to the time you allow the machine to run before you test the following one. But a shorter program can always be just one second further away.

The philosopher Ernst Mach once made the drastic claim that the best thing that science could do is making predictions about phenomena, without explaining the success of such predictions with the (ontological) assumptions of the possible hypotheses. However, the best explanation, and hence possibly the simplest program, can be the ultimate goal of science. And a nice property of this kind of simplicity is that we can measure our progress. We may not have an effective, i.e., computable, method to establish whether a hypothesis is the simplest but given a large amount of data we can establish the relative simplicity of any two hypotheses.

**Conclusion**

I will try to state my conclusion in one sentence, while it is probably not the shortest description of that conclusion:

**Claim 3** In systematic induction we should, given discovered alternatives, prefer the simplest explanation, i.e., the shortest computational description of known data given a hypothesis plus the shortest description of that hypothesis, because it provides more probable predictions.

In my discussion I tried to be as substantial as possible. Those who are interested in a more lengthy discussion, including several other approaches to simplicity, beginning with Aristotle's, can contact me for a copy of my (Van den Bosch 1994).

**References**


A.P.M. van den Bosch Computing Simplicity, About the role of simplicity in discovery, explanation, and prediction. Master thesis, Department of Philosophy, University of Groningen, 1994.