



## Contributors

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**Hans P. Moravec**, author of "Sensor Fusion in Certainty Grids for Mobile Robots" is a senior research scientist at the Robotics Institute, Carnegie-Mellon University, Pittsburgh, PA 15213. As director of the CMU Mobile Robot Laboratory, he pursues projects in mobile robots, computer vision, supercomputers, robot manip-

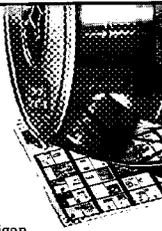
ulators, novel space travel schemes, and computational models of physics. Moravec has interests in computer animation and three dimensional graphics. He has produced illustrations and films presenting progress in the other work and published in the areas of mobile robots, computer vision, robots and the future, orbital skyhooks, switching networks, and three dimensional graphics.

**Gudula Retz-Schmidt** received her Master degree (Dipl.-Inform.) from the University of Hamburg. She is currently working on the VITRA project in the Department of Computer Science, SFB 314, University of Saarbrücken, D-6600 Saarbrücken 11, Federal Republic of Germany. The VITRA project deals with the natural language description of image sequences.

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